

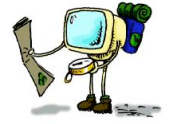
## LECTURE - X DEADLOCKS - I

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## Roadmap

- Deadlocks
  - Deadlock Characterization
  - Deadlock Detection
    - Resource Allocation Graphs
- Classic Problems of Synchronization
  - Bounded Buffer



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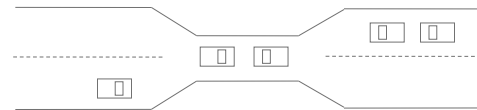
## The Deadlock Problem

- A set of blocked processes each holding a resource and waiting to acquire a resource held by another process in the set.
- Example
  - System has 2 disk drives.
  - $P_1$  and  $P_2$  each hold one disk drive and each needs another one.
- Example
  - semaphores  $A$  and  $B$ , initialized to 1

$P_0$	$P_1$
<code>wait (A);</code>	<code>wait(B)</code>
<code>wait (B);</code>	<code>wait(A)</code>

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## Bridge Crossing Example

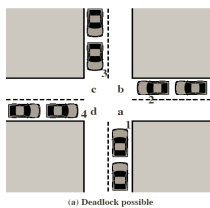


- Traffic only in one direction.
- Each section of a bridge can be viewed as a resource.
- If a deadlock occurs, it can be resolved if one car backs up (preempt resources and rollback).
- Several cars may have to be backed up if a deadlock occurs.

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## Deadlock vs Starvation

- **Deadlock** - two or more processes are waiting indefinitely for an event that can be caused by only one of the waiting processes



(a) Deadlock possible

- **Starvation** - indefinite blocking. A process may never be removed from the semaphore queue in which it is suspended.

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## Deadlock Characterization

Deadlock can arise if four conditions hold simultaneously.

1. **Mutual exclusion:** nonshared resources; only one process at a time can use a specific resource
2. **Hold and wait:** a process holding at least one resource is waiting to acquire additional resources held by other processes
3. **No preemption:** a resource can be released only voluntarily by the process holding it, after that process has completed its task

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## Deadlock Characterization (cont.)

Deadlock can arise if four conditions hold simultaneously.

4. **Circular wait:** there exists a set  $\{P_0, P_1, \dots, P_n\}$  of waiting processes such that  $P_0$  is waiting for a resource that is held by  $P_1$ ,  $P_1$  is waiting for a resource that is held by  $P_2, \dots, P_{n-1}$  is waiting for a resource that is held by  $P_n$ , and  $P_n$  is waiting for a resource that is held by  $P_0$ .

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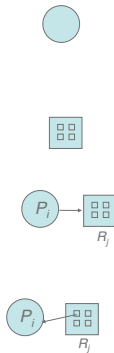
## Resource-Allocation Graph

- Used to describe deadlocks
- Consists of a set of vertices  $V$  and a set of edges  $E$ .
- $V$  is partitioned into two types:
  - $P = \{P_1, P_2, \dots, P_n\}$ , the set consisting of all the processes in the system.
  - $R = \{R_1, R_2, \dots, R_m\}$ , the set consisting of all resource types in the system.
- **P requests R** - directed edge  $P_i \rightarrow R_j$
- **R is assigned to P** - directed edge  $R_j \rightarrow P_i$

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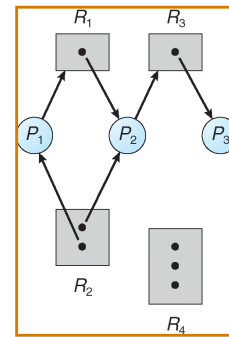
## Resource-Allocation Graph (Cont.)

- Process
- Resource Type with 4 instances
- $P_i$  requests instance of  $R_j$
- $P_i$  is holding an instance of  $R_j$



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## Example of a Resource Allocation Graph



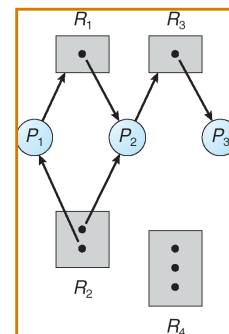
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## Basic Facts

- If graph contains no cycles  $\Rightarrow$  no deadlock.
- If graph contains a cycle  $\Rightarrow$  there may be a deadlock
  - if only one instance per resource type, then deadlock.
  - if several instances per resource type, possibility of deadlock.

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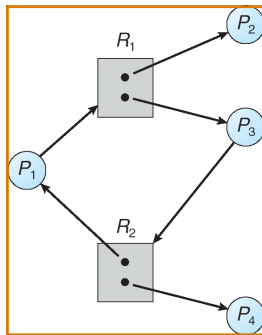
## Resource Allocation Graph - Example 1



$\rightarrow$  No Cycle, no Deadlock

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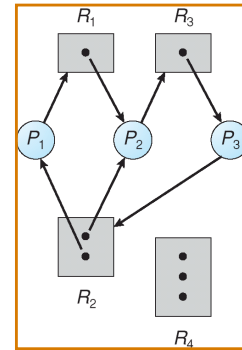
### Resource Allocation Graph - Example 2



→ Cycle, but no Deadlock

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### Resource Allocation Graph - example 3



→ Deadlock

Which Processes  
deadlocked?

→ P1 & P2 & P3

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### Exercise

In the code below, three processes are competing for six resources labeled A to F.

- a. Using a resource allocation graph (Silberschatz pp.249-251) show the possibility of a deadlock in this implementation.

<pre>void P0() {   while (true) {     get(A);     get(B);     get(C);     // critical region:     // use A, B, C     release(A);     release(B);     release(C);   } }</pre>	<pre>void P1() {   while (true) {     get(D);     get(E);     get(B);     // critical region:     // use D, E, B     release(D);     release(E);     release(B);   } }</pre>	<pre>void P2() {   while (true) {     get(C);     get(F);     get(D);     // critical region:     // use C, F, D     release(C);     release(F);     release(D);   } }</pre>
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### Rule of Thumb

- A cycle in the resource allocation graph
  - Is a **necessary condition** for a deadlock
  - But **not a sufficient condition**

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### Classical Problems of Synchronization

- Bounded-Buffer Problem
- Readers and Writers Problem
- Dining-Philosophers Problem
- Sleeping Barber Problem

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### Bounded-Buffer Problem

- Shared buffer with N slots to store at most N items
- Producer processes data items and puts into the buffer
- Consumer gets the data items from the buffer
- Variable empty keeps number of empty slots in the buffer
- Variable full keeps number of full items in the buffer

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## Bounded Buffer - 1 Semaphore Soln

- The structure of the **producer process**

```
int empty=N, full=0;
do {
    // produce an item
    wait (mutex);
    if (empty> 0){
        // add the item to the buffer
        empty --; full++;
    }
    signal (mutex);
} while (true);
```

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## Bounded Buffer - 1 Semaphore Soln

- The structure of the **consumer process**

```
do {
    wait (mutex);
    if (full>0){
        // remove an item from buffer
        full--; empty++;
    }
    signal (mutex);

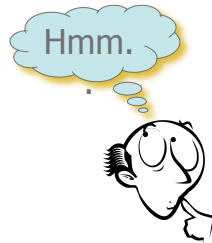
    // consume the removed item

} while (true);
consume non-existing item!
```

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## Summary

- Deadlocks
  - Deadlock Characterization
  - Resource Allocation Graphs
- Classic Problems of Synchronization
  - Bounded Buffer



- Next Lecture: Deadlocks - II
- Reading Assignment: Chapter 7 from Silberschatz.

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## Acknowledgements

- “Operating Systems Concepts” book and supplementary material by A. Silberschatz, P. Galvin and G. Gagne
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