Lecture - VIII
Process Synchronization - I

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Roadmap

- Process Synchronization
- Race Conditions
- Critical-Section Problem
  - Solutions to Critical Section
  - Different Implementations
Background

- Concurrent access to shared data may result in **data inconsistency**
- Maintaining **data consistency** requires mechanisms to ensure the **orderly execution of cooperating processes**
- Consider **consumer-producer** problem:
  - Initially, count is set to 0
  - It is incremented by the producer after it produces a new buffer
  - and is decremented by the consumer after it consumes a buffer.

```java
Producer:
while (true){  /* produce an item and put in nextProduced*/
    while (count == BUFFER_SIZE)
        ; // do nothing
    buffer [in] = nextProduced;
    in = (in + 1) % BUFFER_SIZE;
    count++;}

Consumer:
while (1) {
    while (count == 0)
        ; // do nothing
    nextConsumed = buffer[out];
    out = (out + 1) % BUFFER_SIZE;
    count--;}
/* consume the item in nextConsumed*/
```
Race Condition

- **Race condition**: The situation where several processes access and manipulate shared data concurrently. The final value of the shared data depends upon which process finishes last.

- To prevent race conditions, concurrent processes must be **synchronized**.
  - Ensure that only one process at a time is manipulating the variable counter.

- The statements
  - `counter++;`
  - `counter--;`
    must be performed **atomically**.

- Atomic operation means an operation without interruption.

```
• count++ could be implemented as
  register1 = count
  register1 = register1 + 1
  count = register1

• count-- could be implemented as
  register2 = count
  register2 = register2 - 1
  count = register2
```

- Consider this execution interleaving with “count = 5” initially:
  S0: producer execute `register1 = count`  {register1 = 5}
  S1: producer execute `register1 = register1 + 1`  {register1 = 6}
  S2: consumer execute `register2 = count`  {register2 = 5}
  S3: consumer execute `register2 = register2 - 1`  {register2 = 4}
  S4: producer execute `count = register1`  {count = 6}
  S5: consumer execute `count = register2`  {count = 4}
Race Condition

- Significant race conditions in I/O & variable sharing

```c
char chin, chout; //shared
void echo()
{
    do {
        chin = getchar();
        chout = chin;
        putchar(chout);
    } while (...);
}
```

A: Single-threaded echo

B: Multithreaded echo (lucky)

> ./echo
Hello world!
Hello world!

Race Condition

- Significant race conditions in I/O & variable sharing

```c
char chin, chout; //shared
void echo()
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    do {
        chin = getchar();
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}
```

A: Single-threaded echo

B: Multithreaded echo (unlucky)

> ./echo
Hello world!
Hello world!

> ./echo
Hello world!
e...

Significant race conditions in I/O & variable sharing
Race Condition

Significant race conditions in I/O & variable sharing

In this case, replacing the global variables with local variables did not solve the problem. We actually had two race conditions here:

- One race condition in the shared variables and the order of value assignment
- Another race condition in the shared output stream: which thread is going to write to output first (this race persisted even after making the variables local to each thread)

==> Generally, problematic race conditions may occur whenever resources and/or data are shared (by processes unaware of each other or processes indirectly aware of each other).
Critical Section/Region

- **Critical section/region:** segment of code in which the process may be changing shared data (e.g., common variables)
- No two processes should be executing in their critical sections at the same time --> *prevents race conditions*
- **Critical section problem:** design a protocol that the processes use to cooperate

Critical Section

- **The “indivisible” execution blocks are critical regions**
  - A critical region is a section of code that may be executed by only one process or thread at a time
  
  ![Diagram](image)

  - although it is not necessarily the same region of memory or section of program in both processes
  
  ![Diagram](image)

  ==> but physically different or not, what matters is that these regions cannot be interleaved or executed in parallel (pseudo or real)
Solution to Critical-Section Problem

A solution to the critical-section problem must satisfy the following requirements:

1. **Mutual Exclusion** - If process $P_i$ is executing in its critical section, then no other processes can be executing in their critical sections.

2. **Progress** - If no process is executing in its critical section and there exist some processes that wish to enter their critical section, then the selection of the processes that will enter the critical section next cannot be postponed indefinitely.

3. **Bounded Waiting** - A bound must exist on the number of times that other processes are allowed to enter their critical sections after a process has made a request to enter its critical section and before that request is granted.
   - Assume that each process executes at a nonzero speed.
   - No assumption concerning relative speed of the $N$ processes.
Critical Section

- **We need mutual exclusion from critical regions**
  - Critical regions can be protected from concurrent access by padding them with entrance and exit gates (we'll see how later):
    - A thread must try to check in, then it must check out.

```c
void echo()
{
    char chin, chout;
    do {
        enter critical region?
        chin = getchar();
        chout = chin;
        putchar(chout);
        exit critical region
    } while (...);
}
```

Mutual Exclusion

- **Desired effect: mutual exclusion from the critical region**

1. Thread A reaches the gate to the critical region (CR) before B.
2. Thread A enters CR first, preventing B from entering (B is waiting or is blocked).
3. Thread A exits CR; thread B can now enter.
4. Thread B enters CR.

How is this achieved??
Mutual Exclusion

**Implementation 1 — disabling hardware interrupts**

1. thread A reaches the gate to the critical region (CR) before B
   
2. as soon as A enters CR, it disables all interrupts, thus B cannot be scheduled
   
3. as soon as A exits CR, it enables interrupts; B can be scheduled again
   
4. thread B enters CR

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**Implementation 1 — disabling hardware interrupts**

- it works, but not reasonable!
- what guarantees that the user process is going to ever exit the critical region?
- meanwhile, the CPU cannot interleave any other task, even unrelated to this race condition
- the critical region becomes one **physically** indivisible block, not logically
- also, this is not working in multi-processors

```c
void echo()
{
    char chin, chout;
    do {
        disable hardware interrupts
        chin = getchar();
        chout = chin;
        putchar(chout);
        enable hardware interrupts
    } while (...);
}
```
Summary

- Process Synchronization
- Race Conditions
- Critical-Section Problem
  - Solutions to Critical Section
  - Different Implementations

- Next Lecture: Synchronization - II
- Reading Assignment: Chapter 6 from Silberschatz.

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